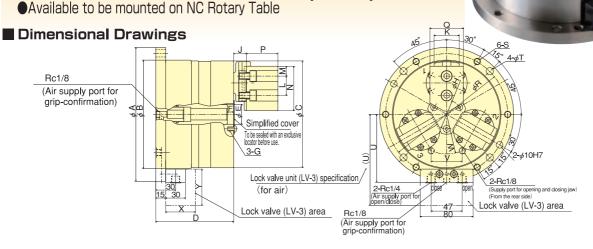


# **Power Wing Work Gripper PWS06**

# Suitable for 3 to 5-Axis machines Cost reduction achieved by built-in Cylinder

- •Stationary clamping by pull back the workpiece Suitable for rough machining, OP-10 or OP-20 with reduced setup time.
- Cost reduction achieved by built-in Cylinder
- Available on the standard column of machine
  \*Total height is reduced by built-in Cylinder.
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- \*No need to introduce separated Cylinder for Chuck.



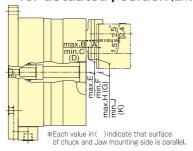
■ **Dimensions** \*The dimensions of (U)/X/Y marked are the size of LV-3(Lock-valve).

Dimensions Model	A h7	В	С	D	E +0.02	F	G	Н	J	K	L	М	N	Р	Q	R (±0.2)	S	Т	U	(U)	V	w	Х	Υ
PWS06	203	164.5	162	118	30.17	3.5	M6 Depth 12	44	19.3	38.07	29.36	15	67.5	47.7	50.8	185	M10	11	103	138	47	60	45	55

Specifications \*\*Clamping force varies in clamping state for jaws and workpiece. \*\*Air Consumption = Under Pressure 0.6MPa Plunger Stroke per 10mm

Dimensions	I lui bci	Jaw	Gripping Fo	Max. allowable pressure MPa (kgf/cm²)		Iviin, allowable	Gripping range mm				Net Weight with	Air Consumption	
Model	Stroke mm	Stroke (diameter) mm	Pneumatic at 0.6MPa (6kgf/cm²)	Hydraulic at 1.3MPa (13kgf/cm²)			pressure MPa (kgf/cm²)	exter Max.	nal φ Min.	Inter	ιιαι ψ	Soft top jaws kg	(N l )
PWS06	11.1	7.7	19 (1937)	53 (5404)	0.7(7)	1.3(13)	0.2(2)	120	12.7	152	70	24	0.54

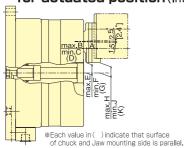
#### Dimensional Drawing for actuated position (External Gripping)



## **■ Dimensions for actuated position** (External Gripping)

Dimensions Model	А	В	O	D	Е	F	G	Н	J	K
PWS06	15.50	4.96	3.05	3.80	20.06	18.89	19.33	20.70	18.48	19.33

#### Dimensional Drawing for actuated position (Internal Gripping)



## **■Dimensions for actuated position** (Internal Gripping)

Dimensions Model	Α	В	С	D	Е	F	G	Н	J	К
PWS06	15.03	5.59	3.43	4.27	16.28	15.08	15.53	17.17	14.52	15.53